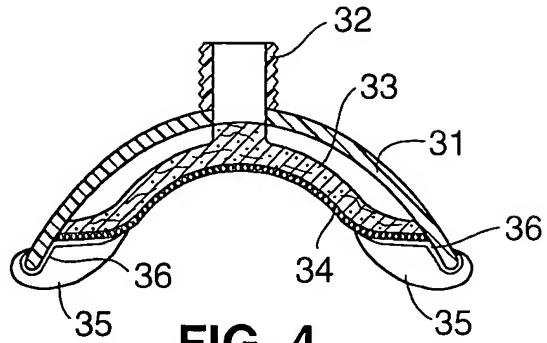
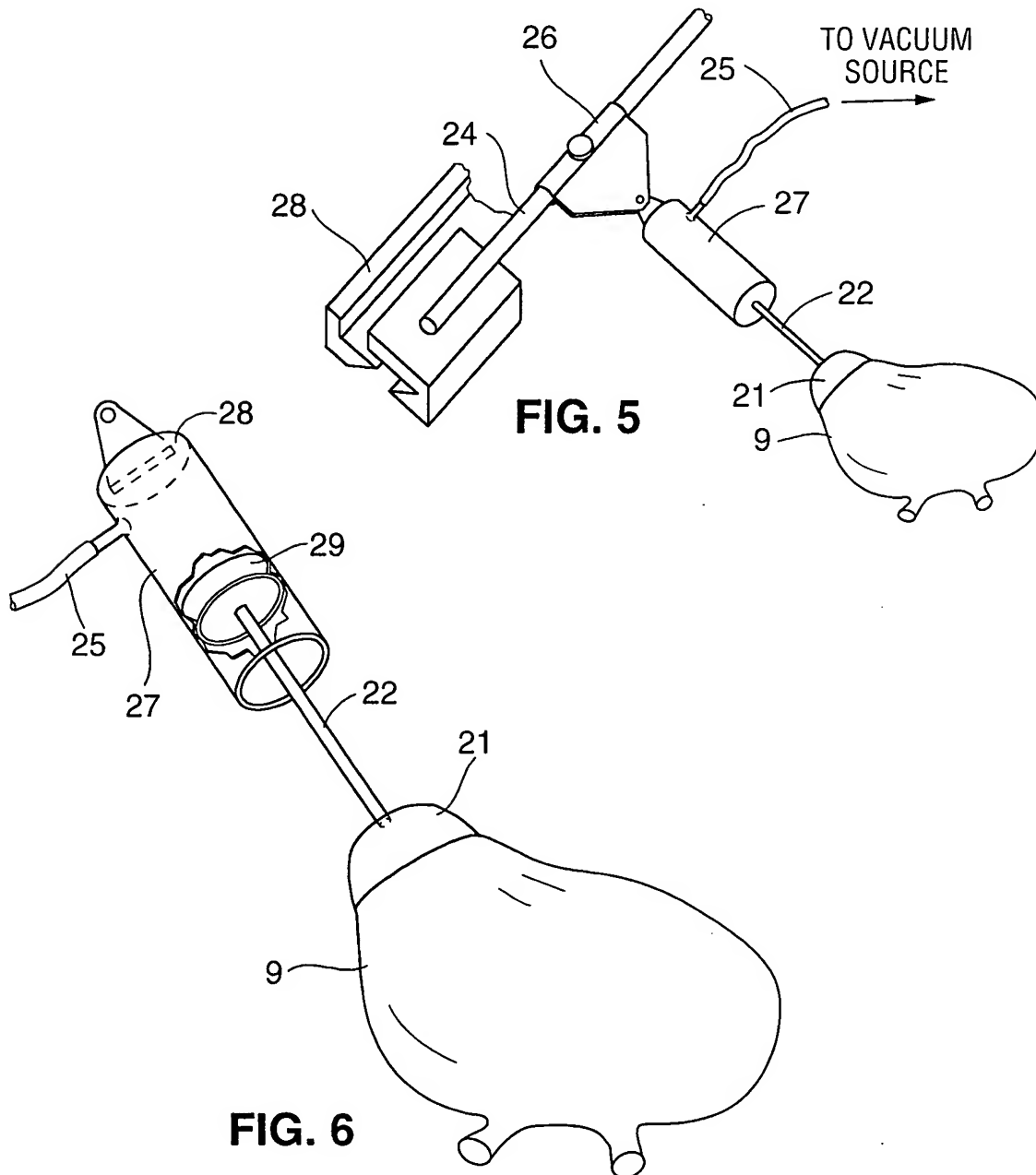


**FIG. 3**

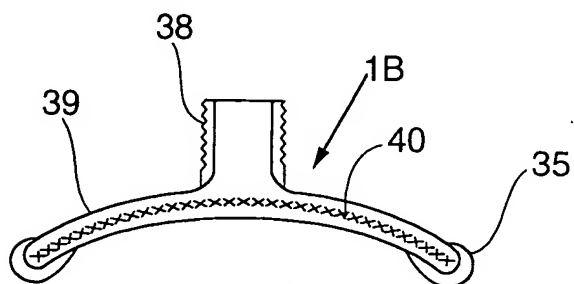
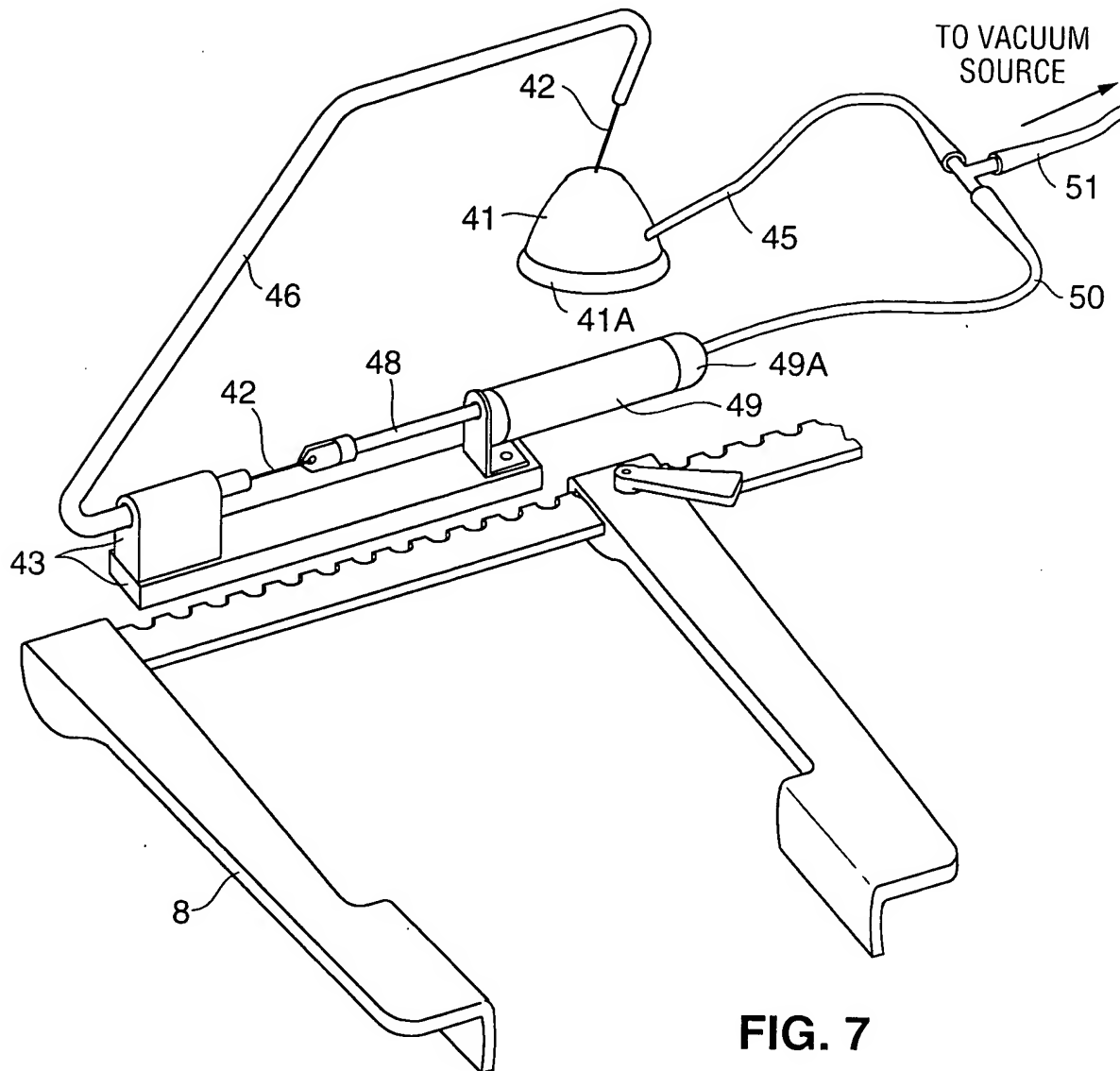


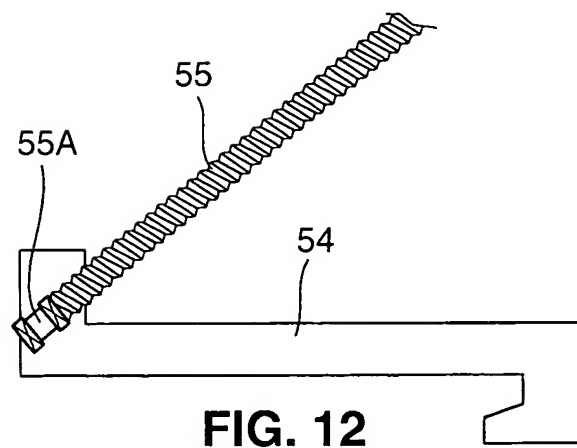
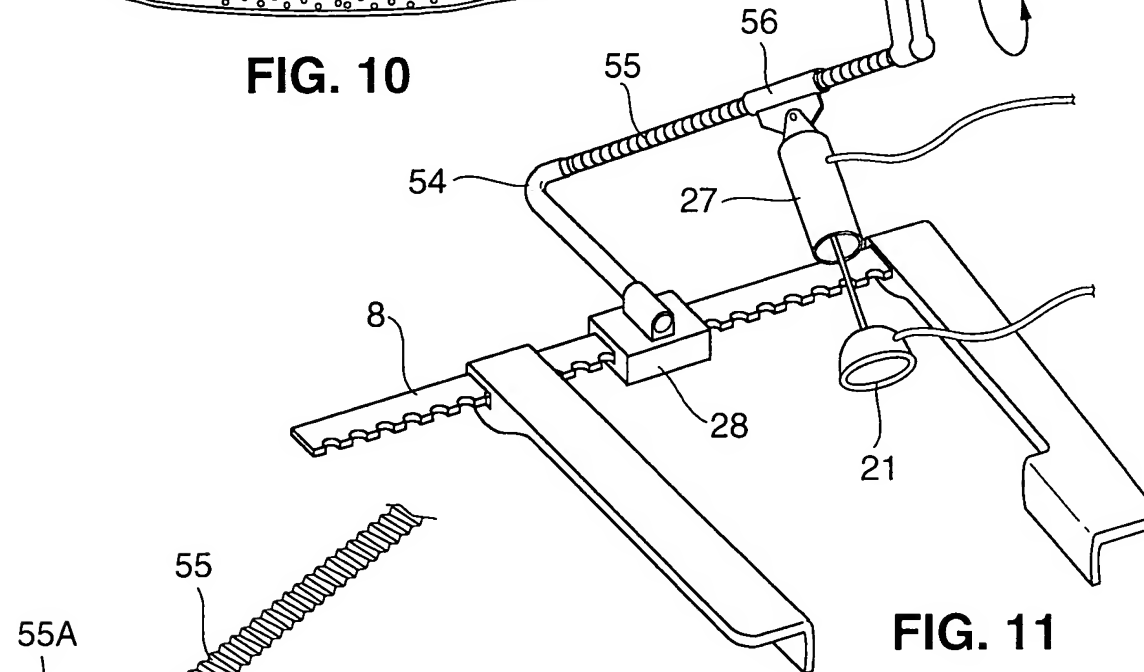
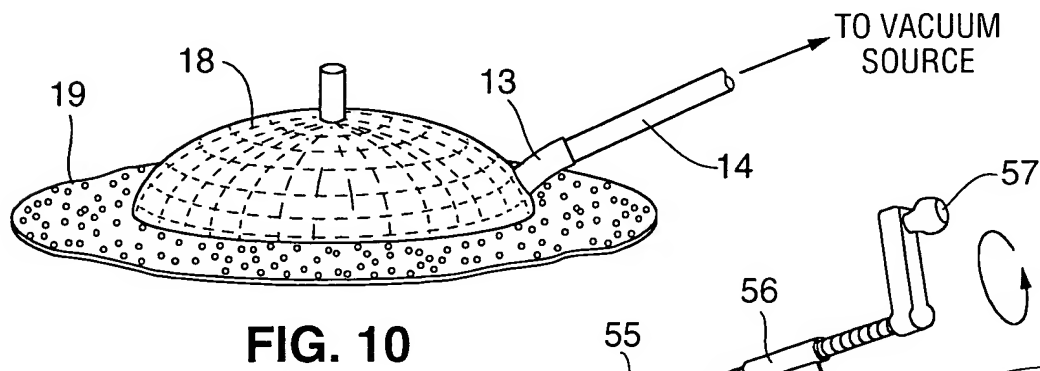
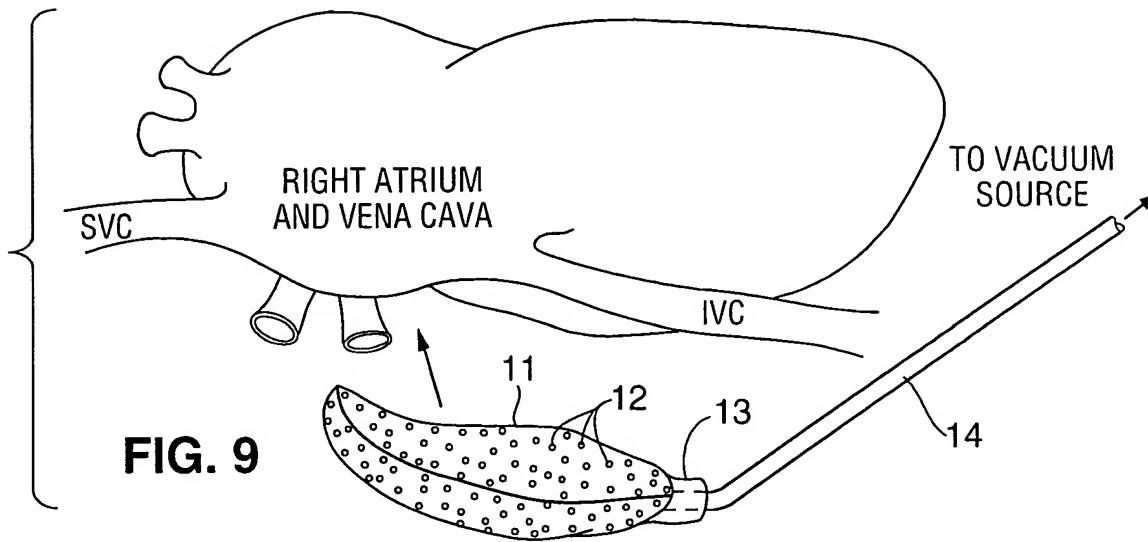
**FIG. 4**

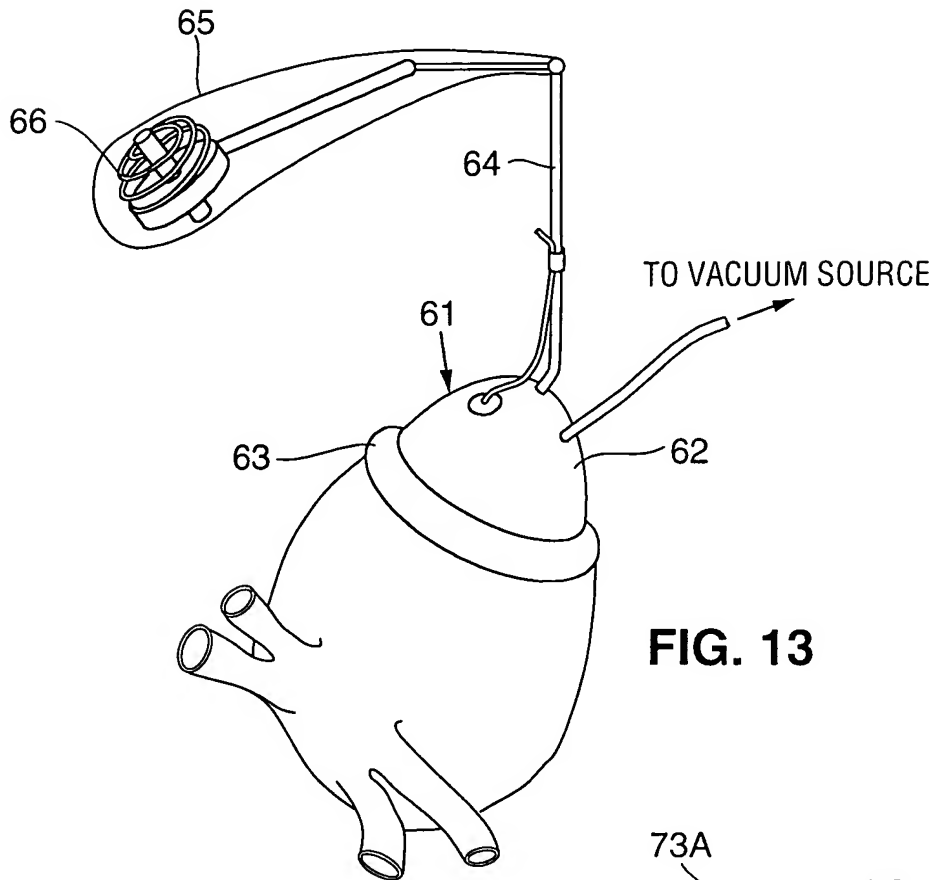


**FIG. 5**

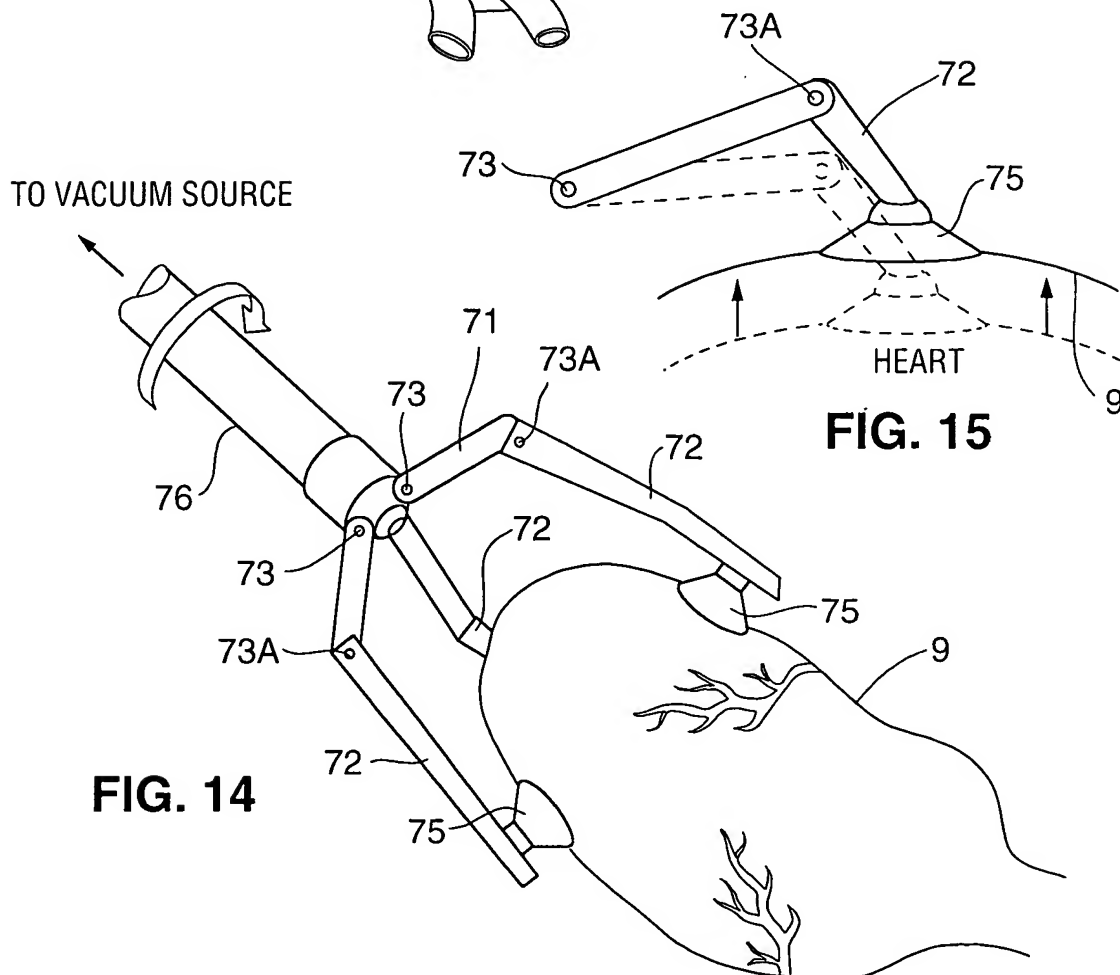
**FIG. 6**





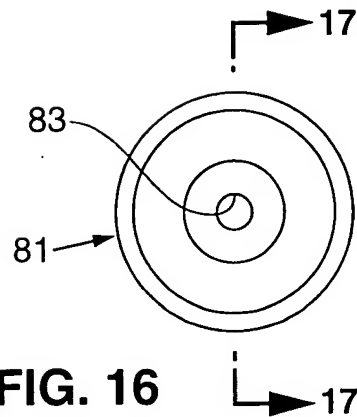


**FIG. 13**

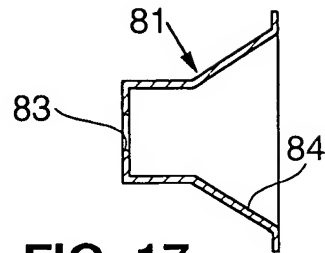


**FIG. 15**

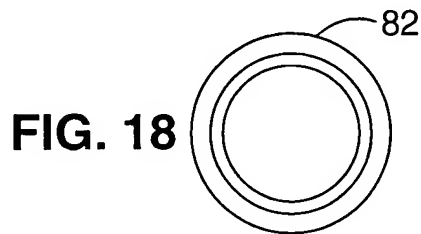
**FIG. 14**



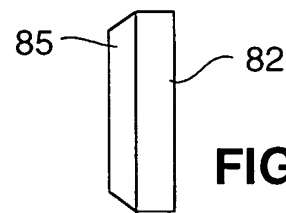
**FIG. 16**



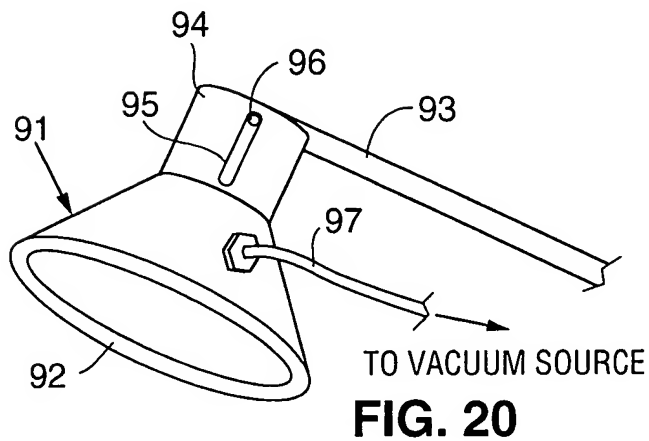
**FIG. 17**



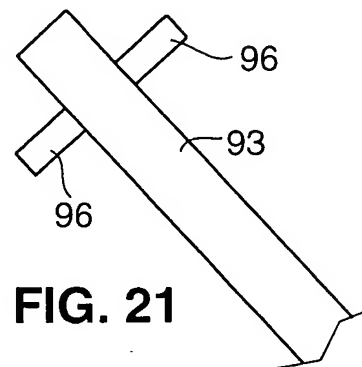
**FIG. 18**



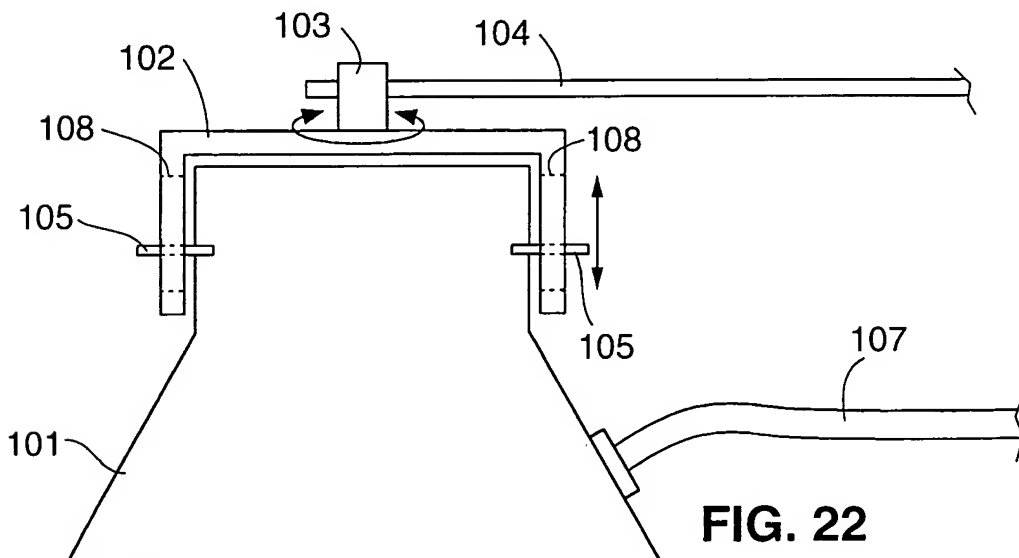
**FIG. 19**



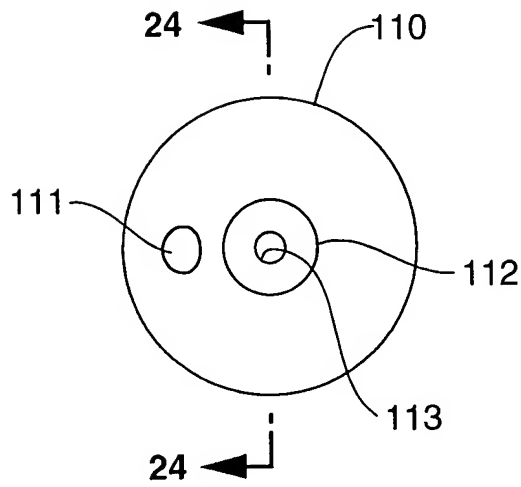
**FIG. 20**



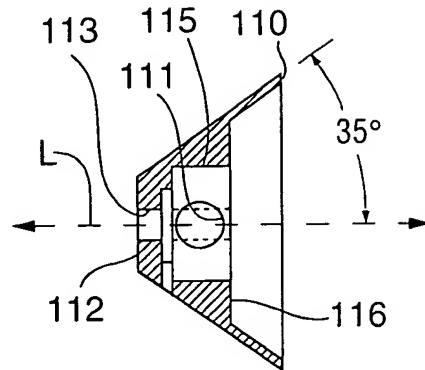
**FIG. 21**



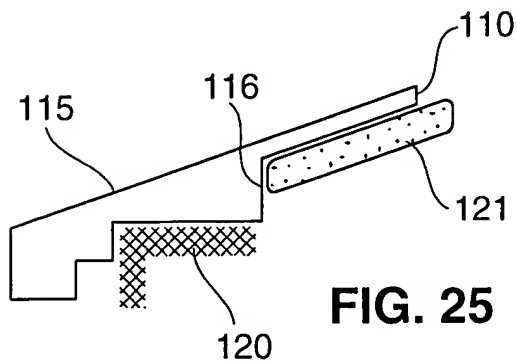
**FIG. 22**



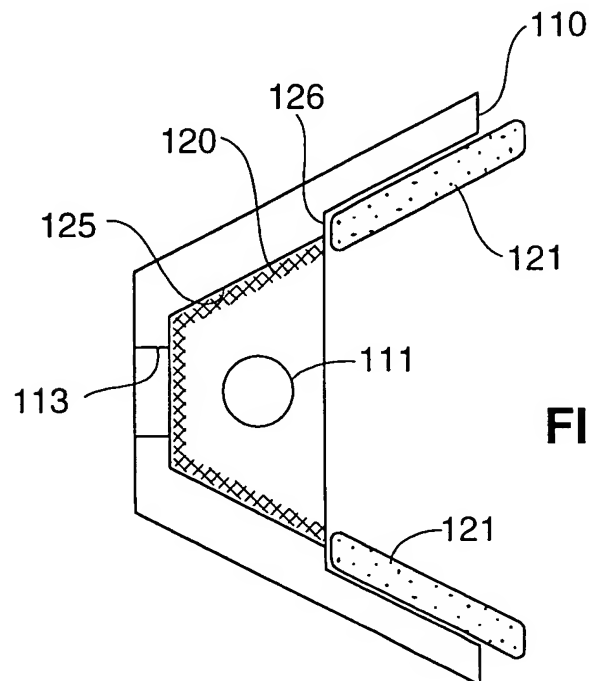
**FIG. 23**



**FIG. 24**



**FIG. 25**



**FIG. 26**



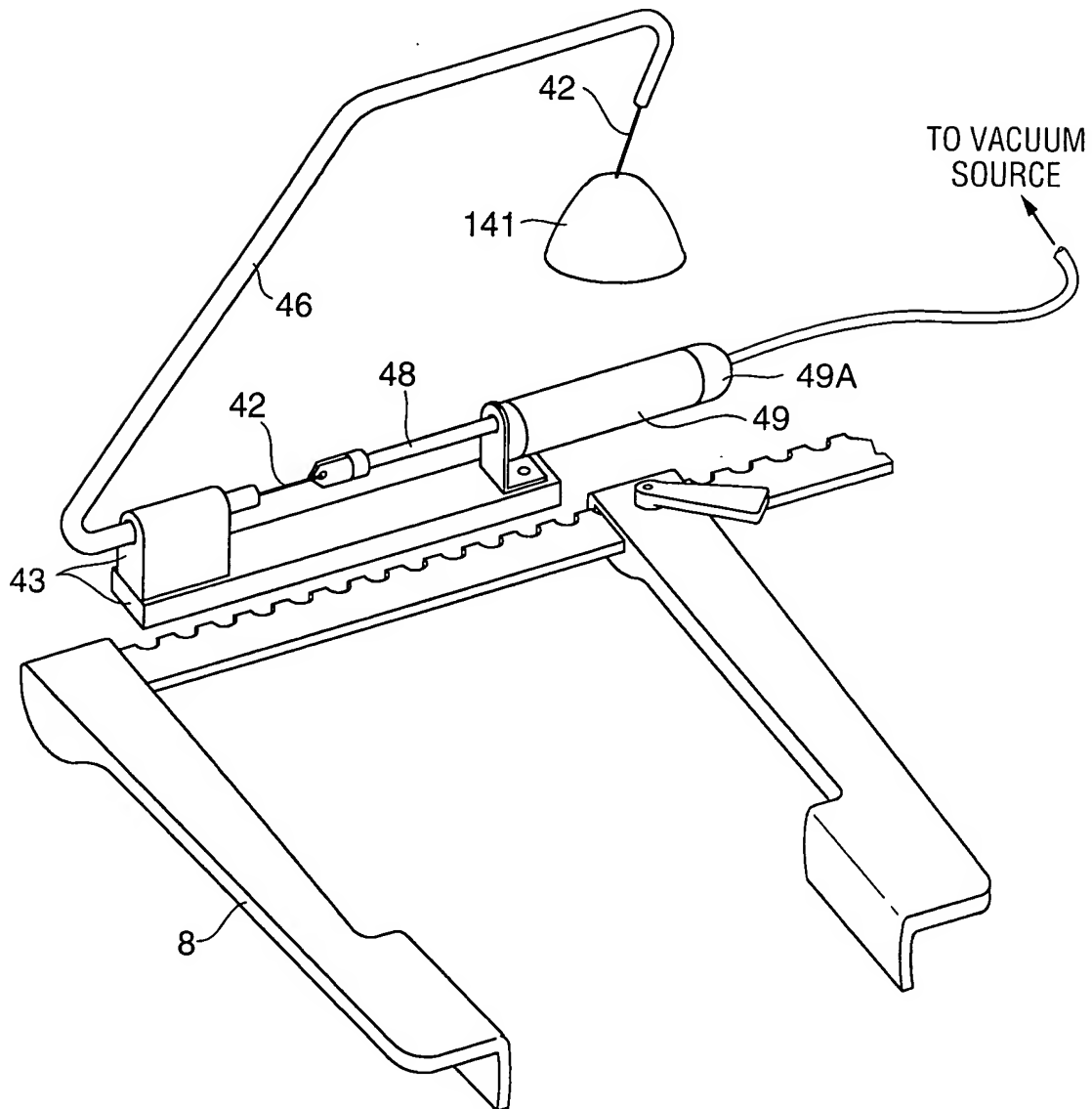
Title: "Organ Manipulator Having Suction Member  
Supported with Freedom to Move Relative to its  
Support"

Inventor: Steven Peng et al.

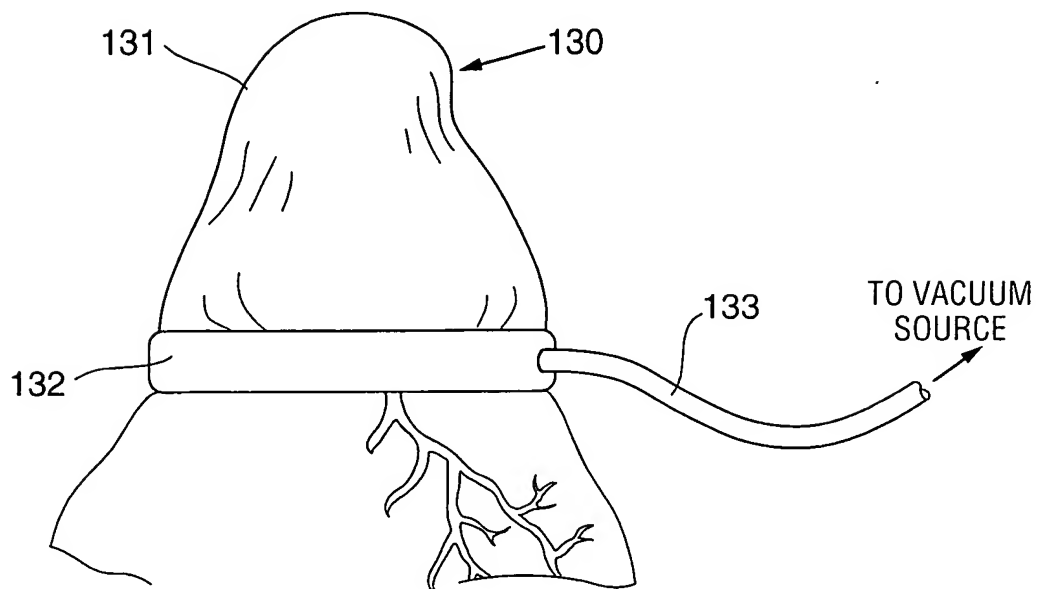
Application No.: Unassigned

Atty. Docket No. GUID-028CON2

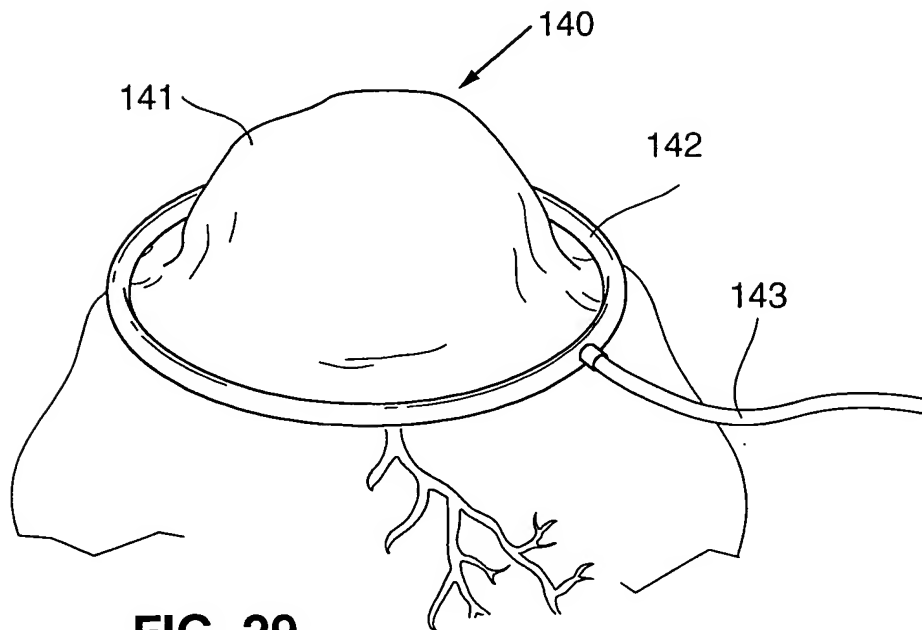
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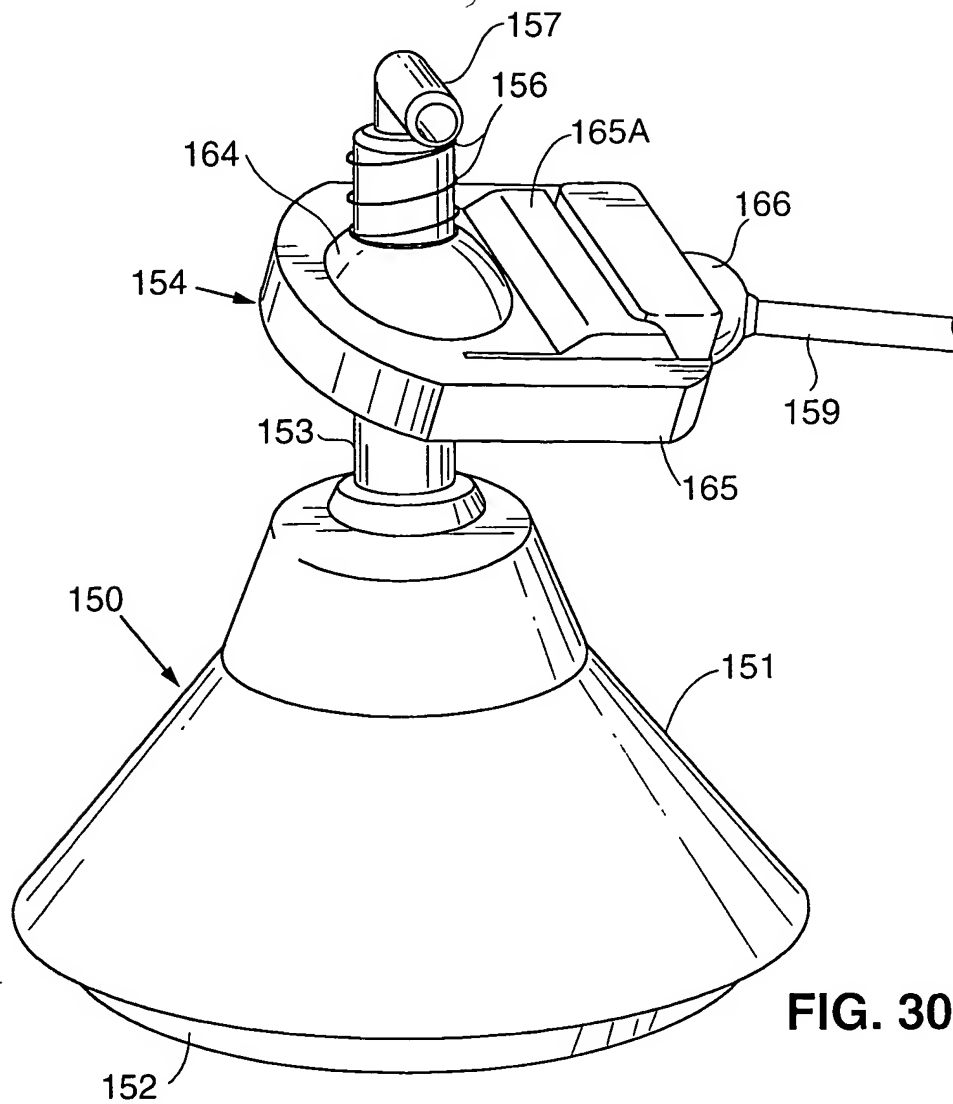
**FIG. 27**



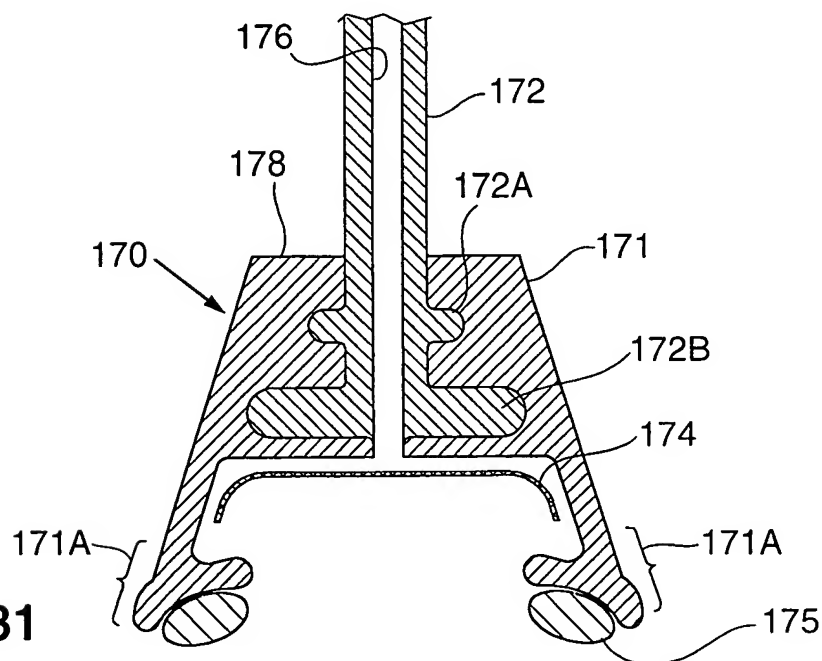
**FIG. 28**



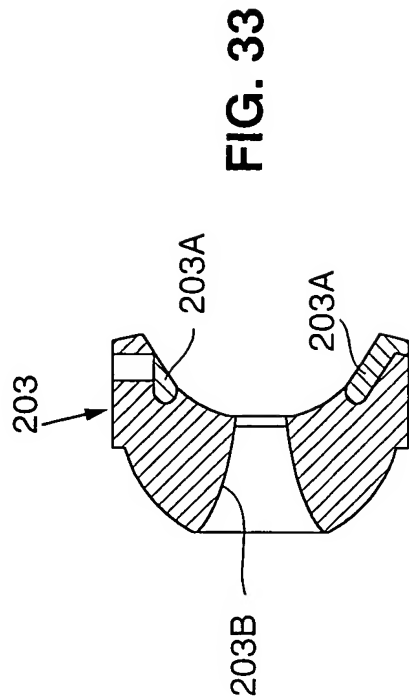
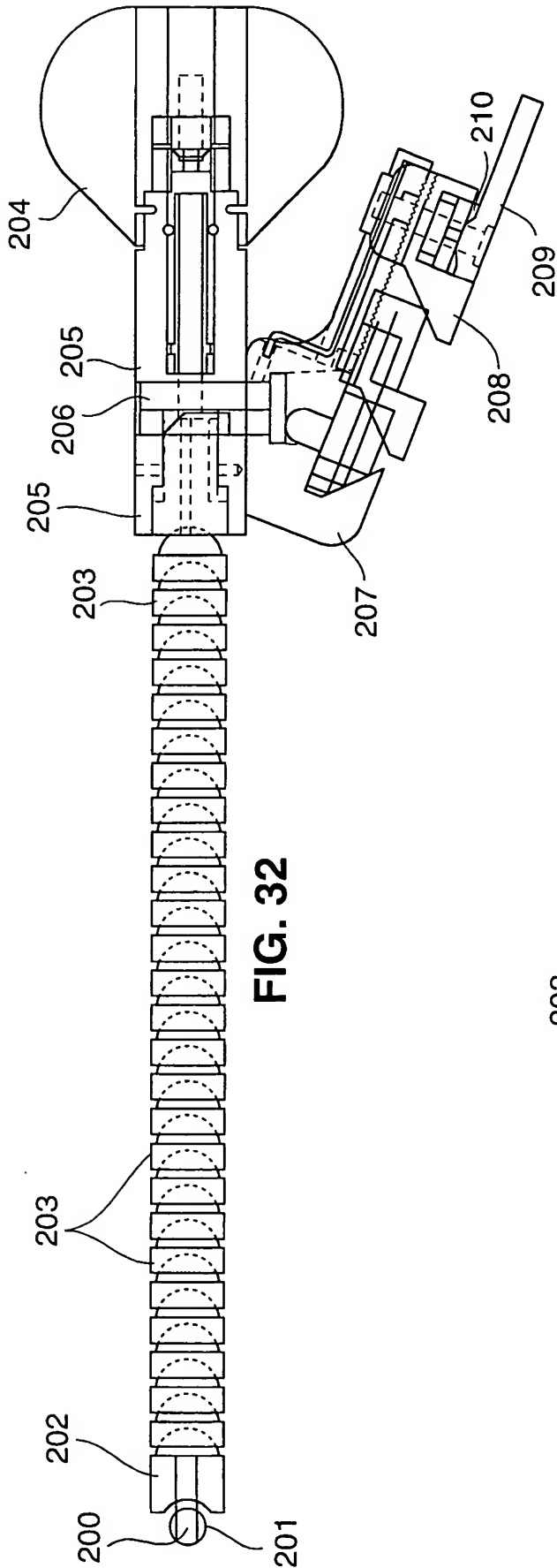
**FIG. 29**

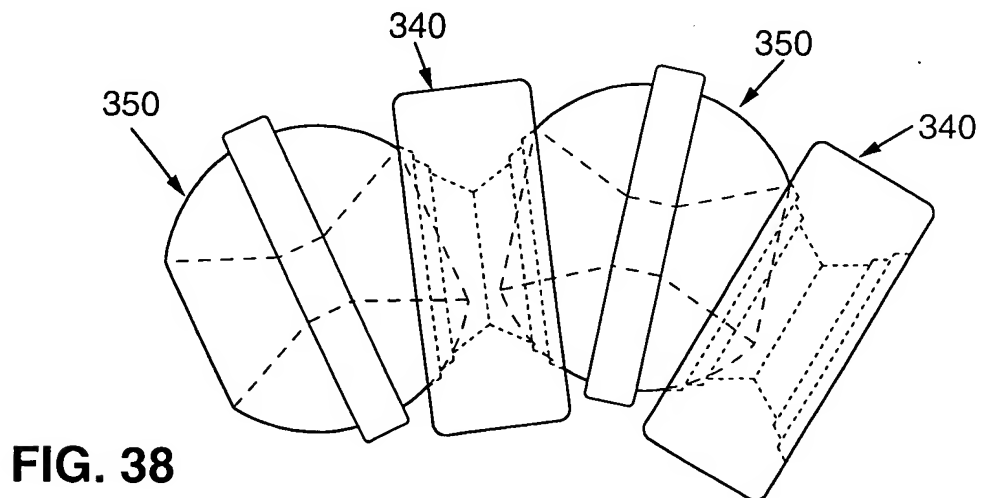
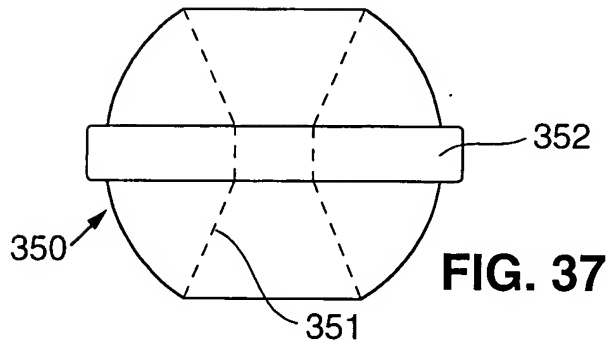
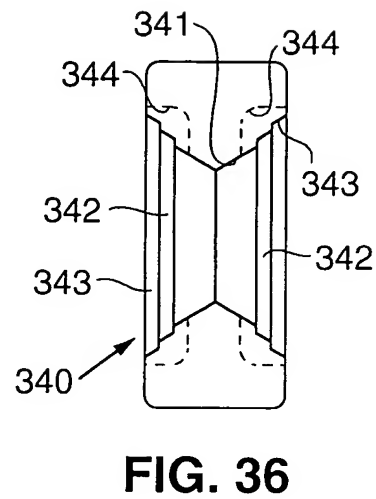
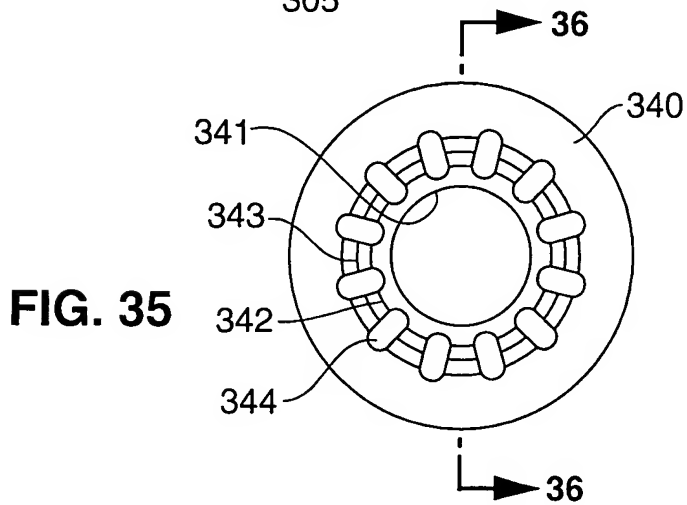
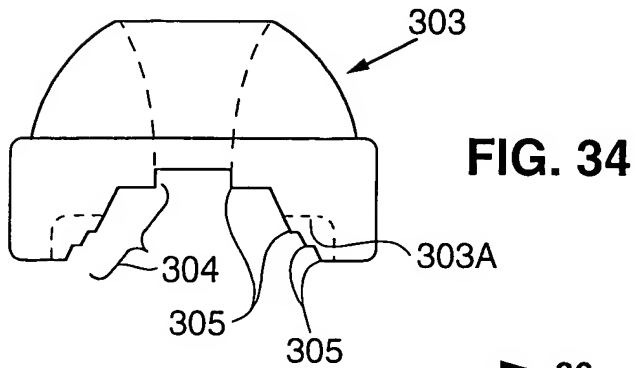


**FIG. 30**



**FIG. 31**





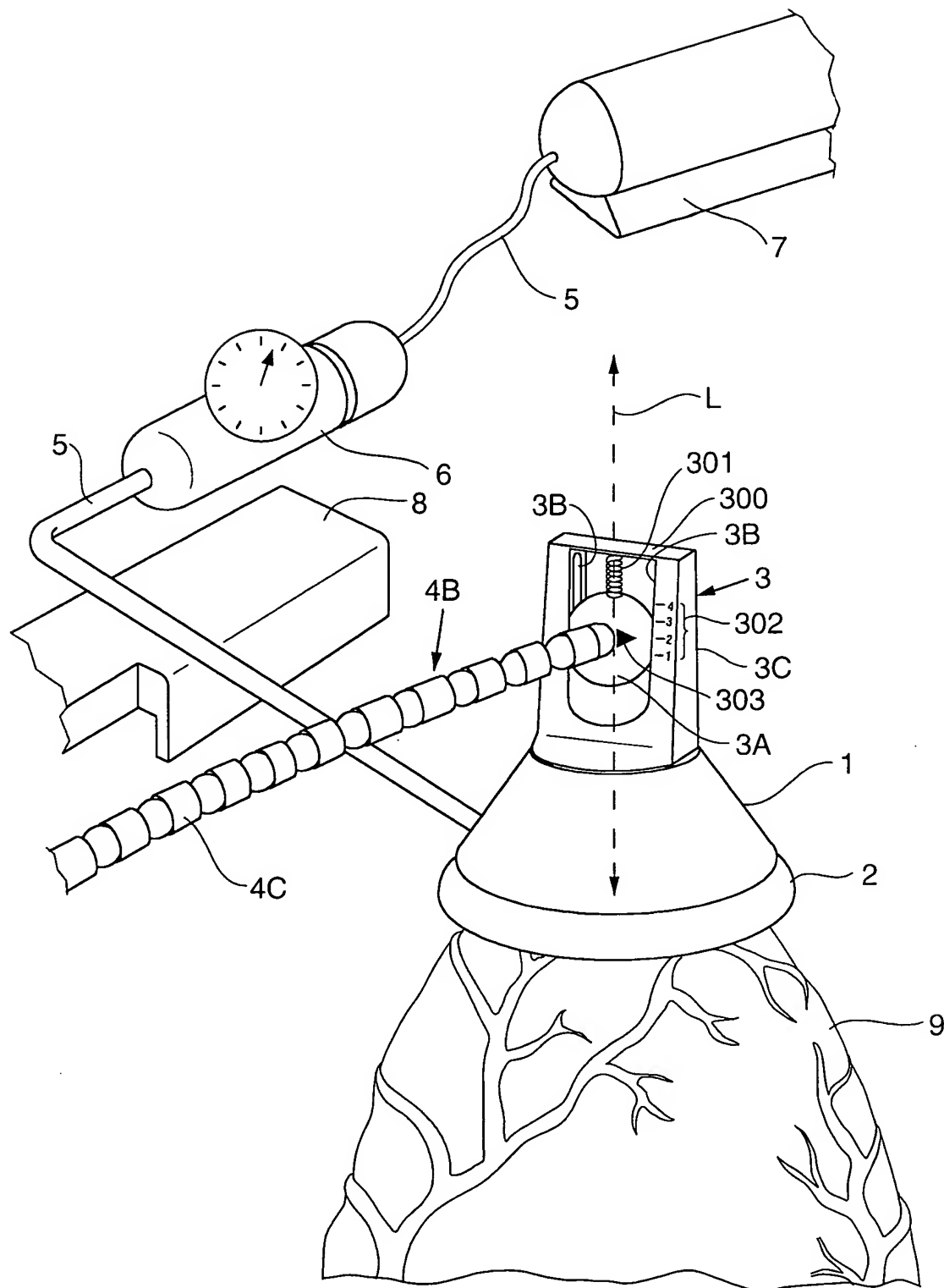


FIG. 39